

# Fundamental Aeronautics Program

## *Subsonic Rotary Wing Project*

### Variable-Speed Rotorcraft Drive System Research

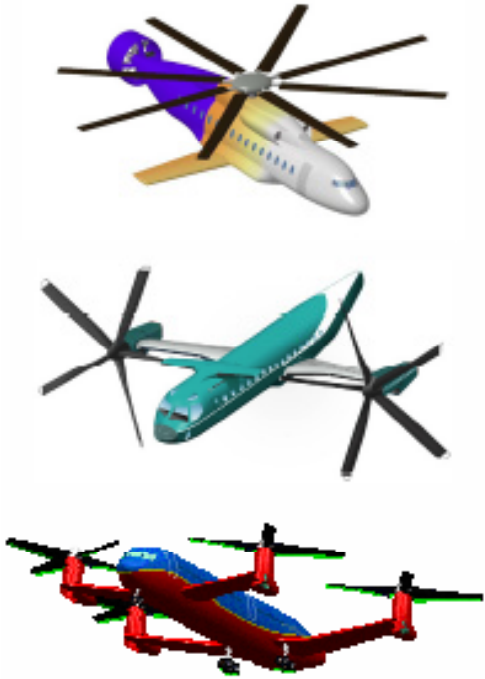
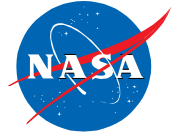
Dr. David G. Lewicki  
Research Mechanical Engineer  
RXN/Tribology & Mechanical Components Branch, Glenn Research Center

Mark Stevens, Mechanical & Rotating Systems Branch, Glenn Research Center  
Hans DeSmidt, Associate Professor, University of Tennessee

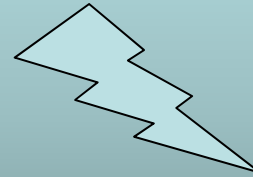


2012 Technical Conference  
March 13-15, 2012

# Background



**High speed**



**Variable-speed  
propulsion (50%)**

## **Applications:**

- Large civil tilt rotor
- Joint heavy lift
- Unmanned air vehicle

## **References:**

- Johnson, W., Yamauchi, G.K., and Watts, M.E., "NASA Heavy Lift Rotorcraft Systems Investigation", NASA/TP-2005-213467, Rept-A-0514419, December 2005.
- Acree, C.W., Hyeonsoo, Y., and Sinsay, J. D., "Performance Optimization of the NASA Large Civil Tiltrotor" International Powered Lift Conference, London, UK, July 22-24, 2008.

# Objective

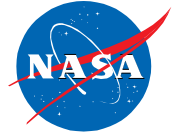
---



**Develop variable-speed drive  
system technologies for rotorcraft  
applications to allow 50% speed  
change of rotors with minimal  
impact on weight.**

# State-of-the-Art

---



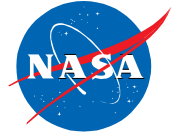
- **Most current rotorcraft operate at fixed speed.**
- **V22: 15% speed change, slowing down engine.**
- **A160 Hummingbird: two-speed transmission, relatively heavy.**
- **Automotive: heavy, not enough power capacity.**



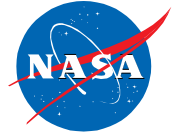
- **Innovative speed change technology required, continued drive system weight reduction required.**

# Approach

---

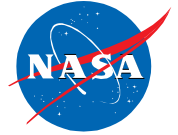


- **Development of variable-speed transmission test facility (in-house).**
- **Development of variable-speed transmission concepts (in-house, industry).**
- **Dynamic modeling of variable-speed drive systems (NASA NRA, Penn St, Univ. of Tennessee).**

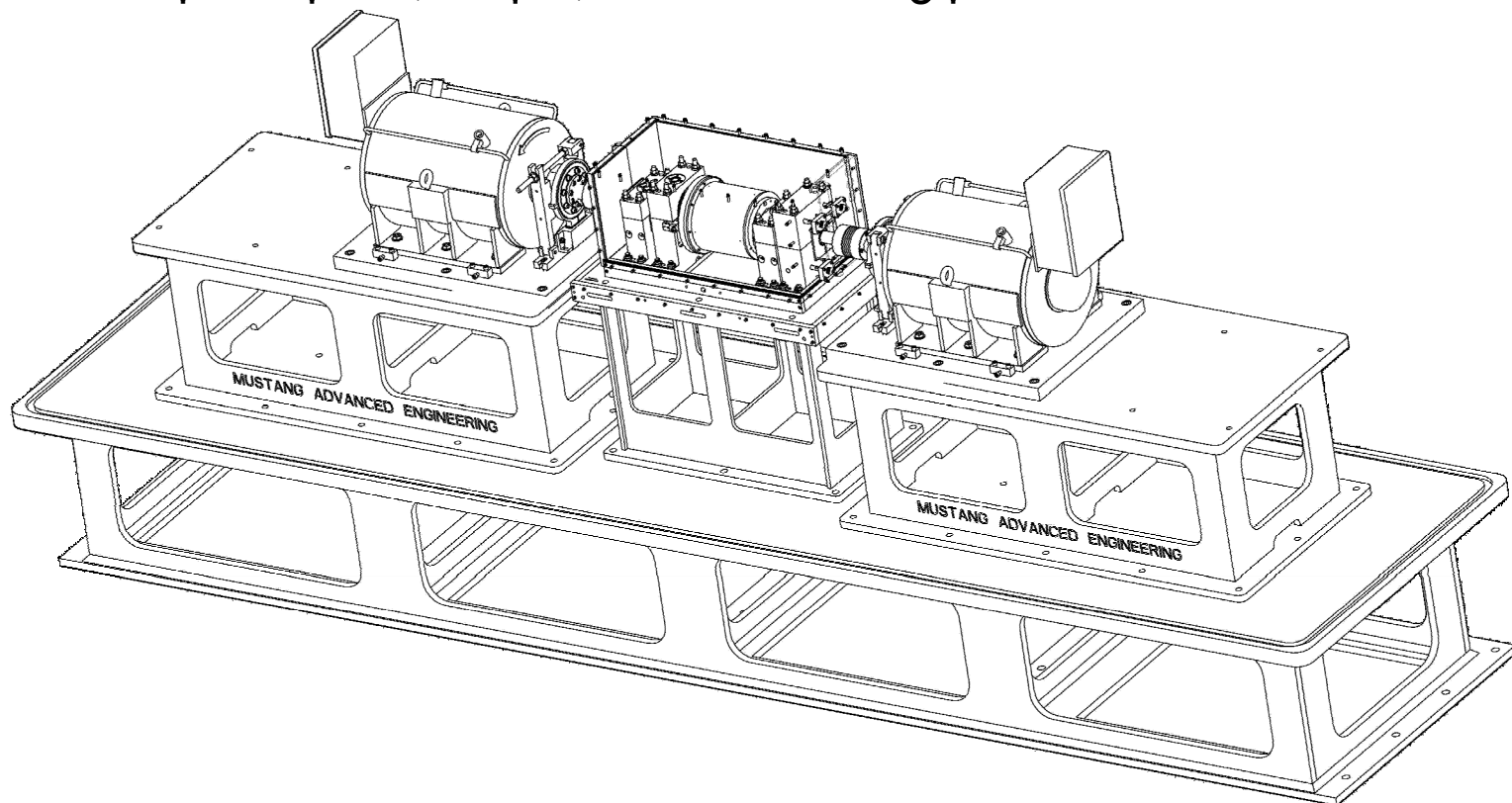


- **Development of variable-speed transmission test facility (in-house).**
- **Development of variable-speed transmission concepts (in-house, industry).**
- **Dynamic modeling of variable-speed drive systems (NASA NRA, Penn St, Univ. of Tennessee).**

# GRC Variable-Speed Transmission Test Facility

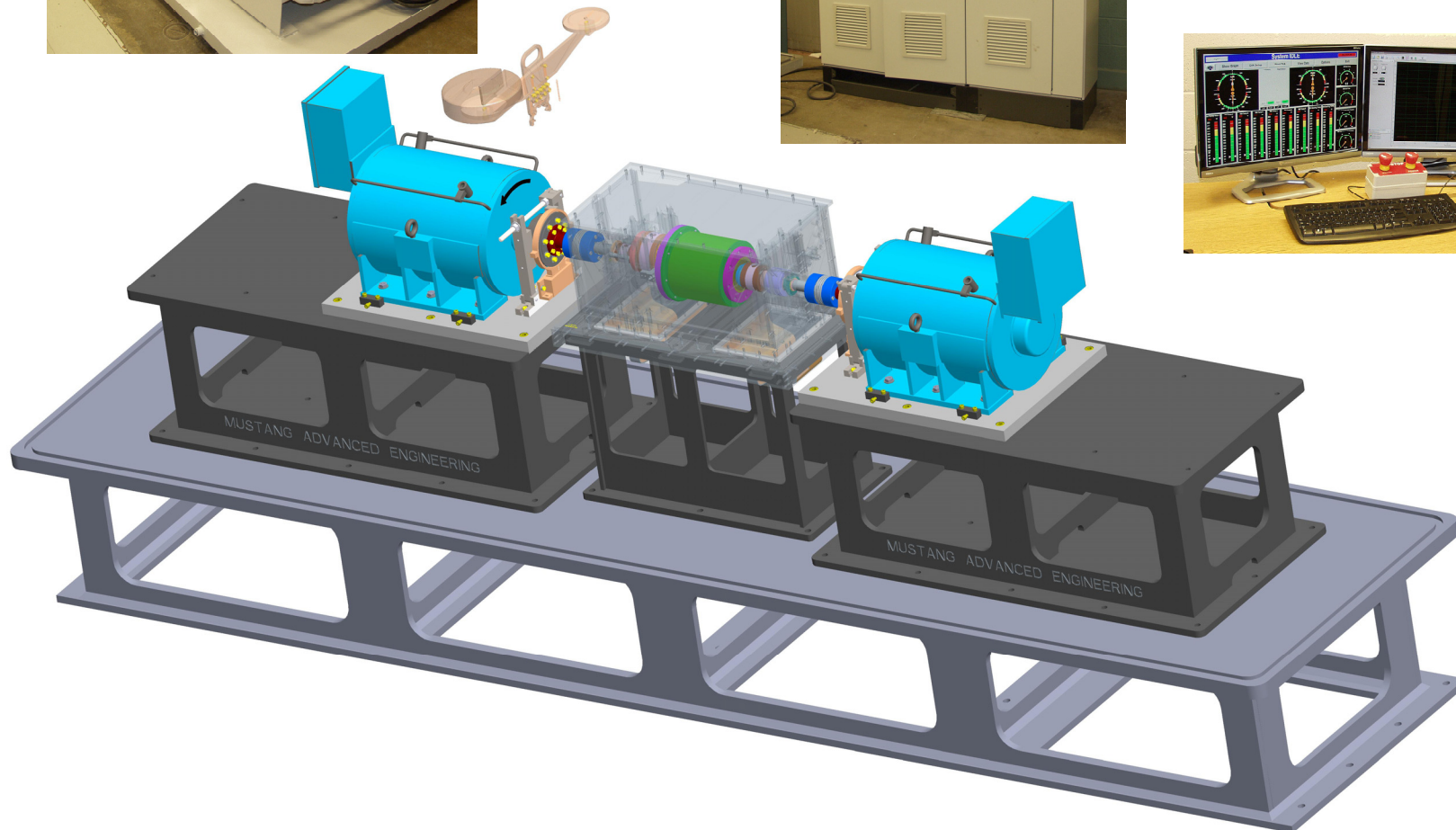
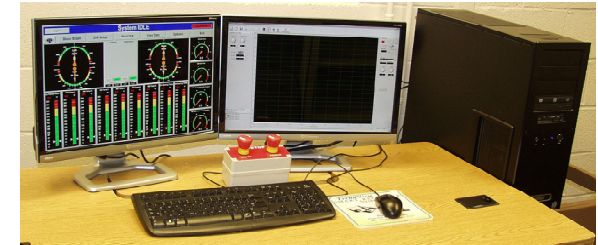
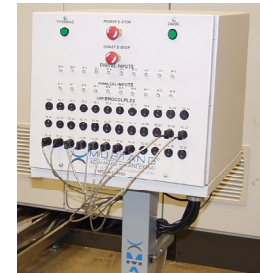
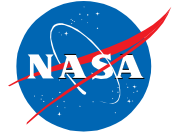


- Dual-motor (driver & loader) facility configuration: allows versatility in allowable designs available to test.
- 15000 rpm input speed, 7500-15000 rpm output speed (0-50% reduction ratio).
- Motor power: 140 ft-lb from 0-7500 rpm, 200-hp from 7500-15000 rpm.
- Power regenerative motor configuration.
- State-of-the-art motor controllers & PLC's.
- Allows scripted speed, torque, & clutch loading profiles.





# GRC Variable-Speed Transmission Test Facility

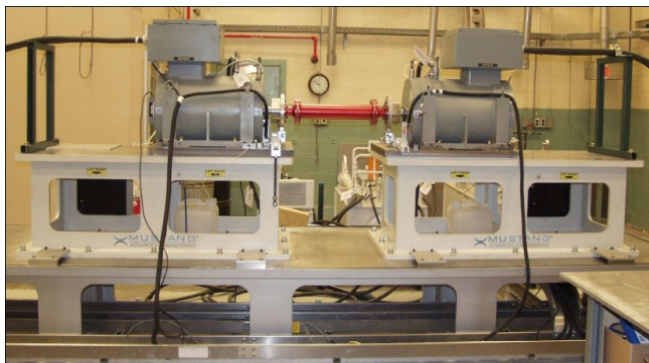




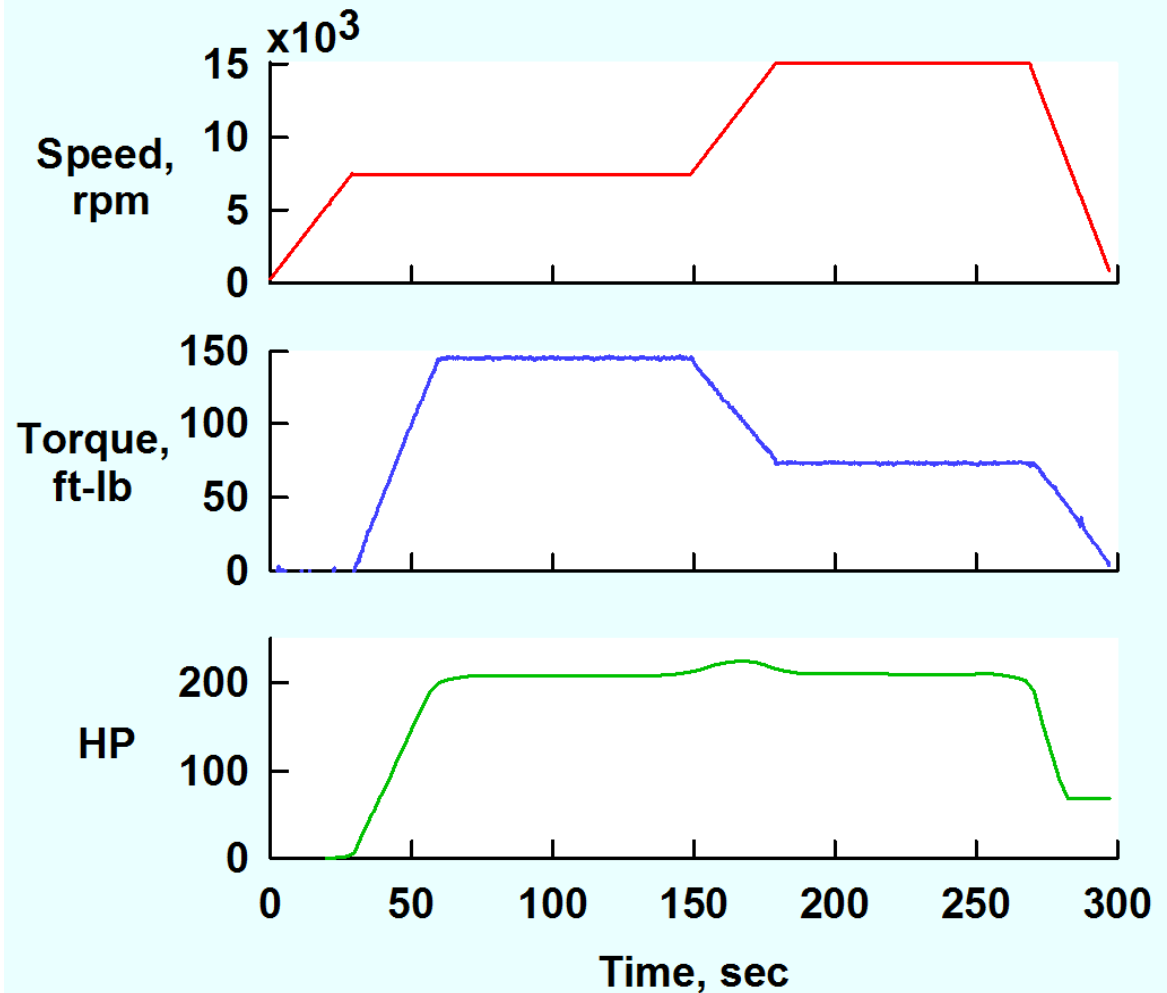
# Facility Validation Tests Completed



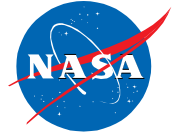
- **Successfully operated at full speed & torque.**
- **Successfully demonstrated prescribed speed & torque control.**



GRC Variable-Speed Transmission  
Test Facility



Facility Check-Out Test Results



- **Development of variable-speed transmission test facility (in-house).**
- **Development of variable-speed transmission concepts (in-house, industry).**
- **Dynamic modeling of variable-speed drive systems (NASA NRA, Penn St, Univ. of Tennessee).**

# Configurations To Test

---

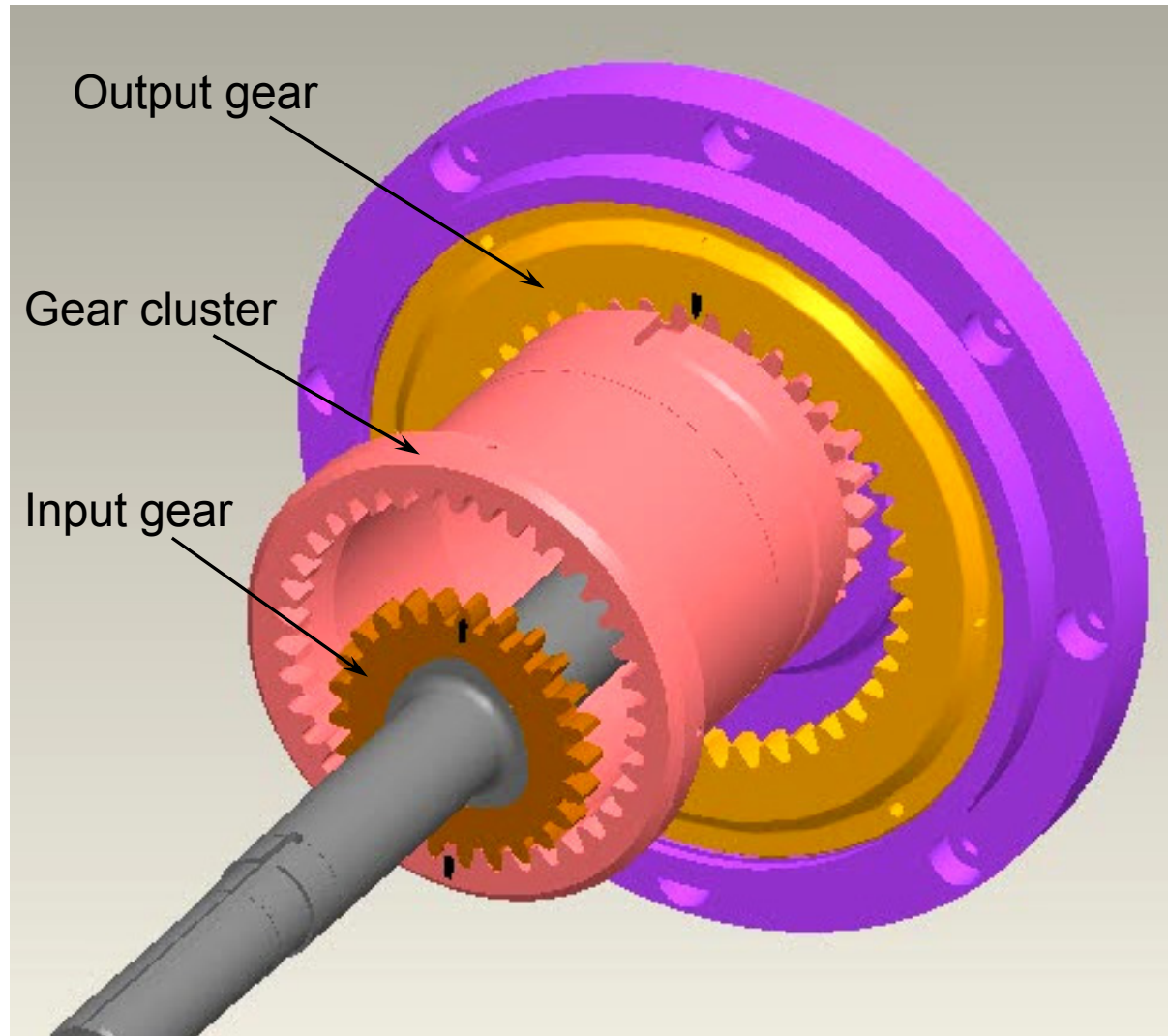
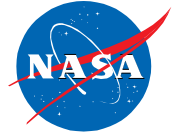


- 1) Offset Compound Gear Drive w/ Dry Clutch.**
- 2) Offset Compound Gear Drive w/ Wet Clutch.**
- 3) Double Star Idler Planetary w/ Dry Clutch.**
- 4) Double Star Idler Planetary w/ Wet Clutch.**

<sup>1</sup> Stevens, M.A., Handschuh, R.F., and Lewicki, D.G., "Concepts for Variable/Multi-Speed Rotorcraft Drive System", Proceedings of the 64th American Helicopter Society International Forum, Montreal, Canada, April-May 2008 (also NASA TM-2008-215276, Army Research Laboratory Report ARL-TR-4564, AHS Paper No. 080273).

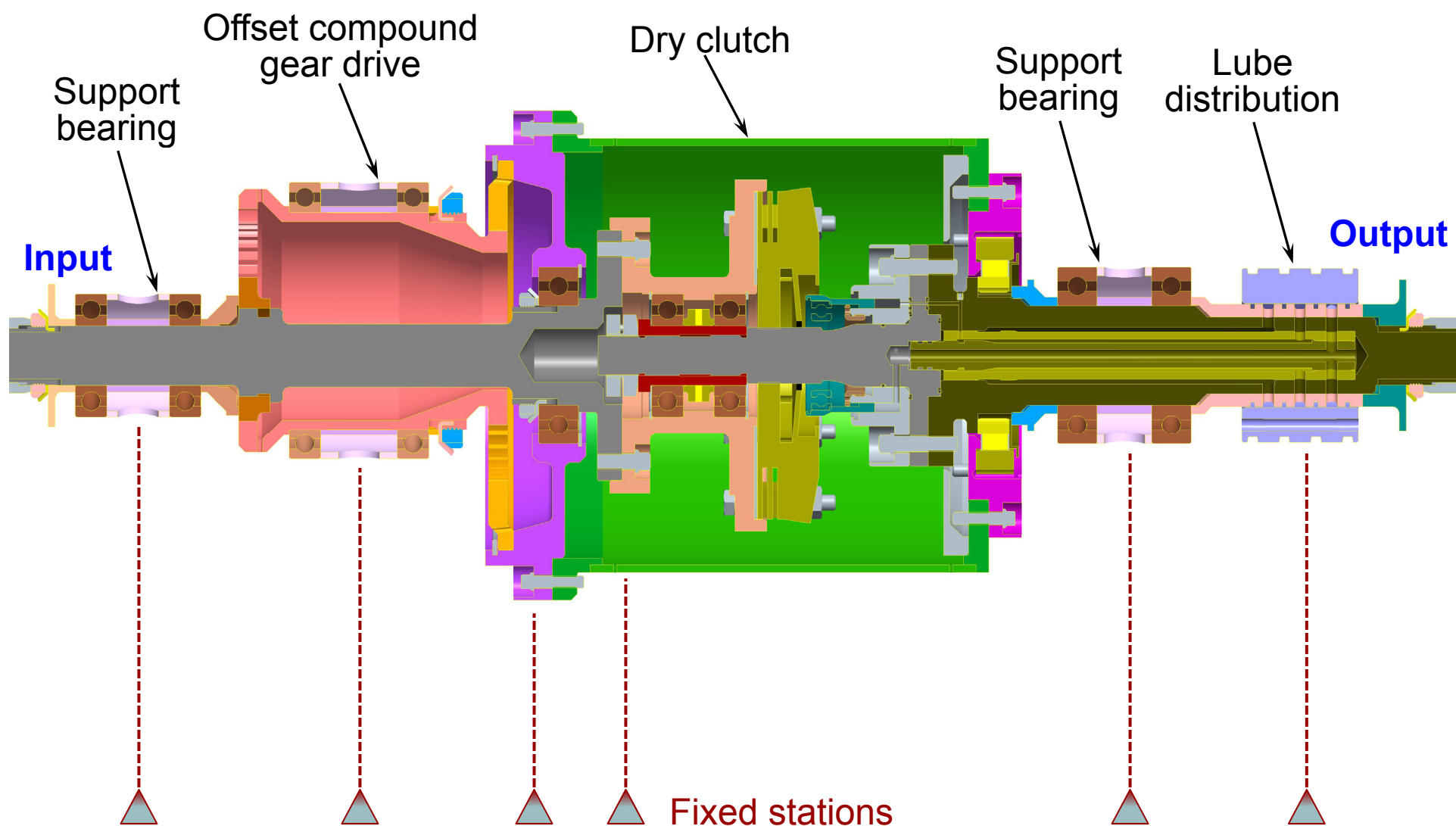
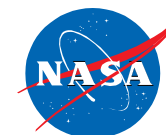
<sup>2</sup> Stevens, M.A., Handschuh, R.F., and Lewicki, D.G., "Variable/Multispeed Rotorcraft Drive System Concepts", NASA TM-2009-215456, Army Research Laboratory Report ARL-TR-4758, March 2009.

# Offset Compound Gear Drive

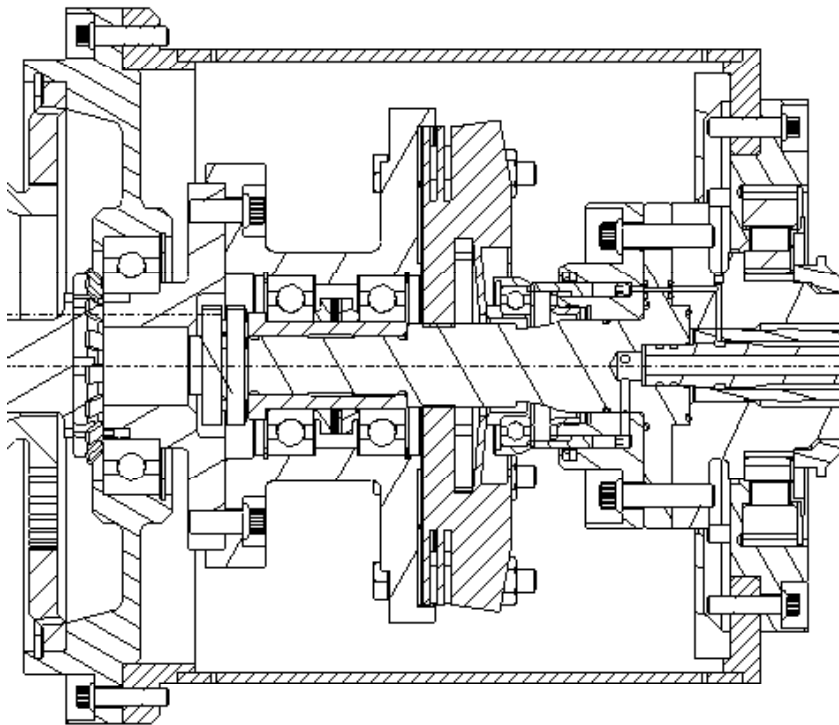


"Offset Compound Gear Inline Two-Speed Drive",  
U.S. Patent No. US 8,091,445 B1, Jan 10, 2012.

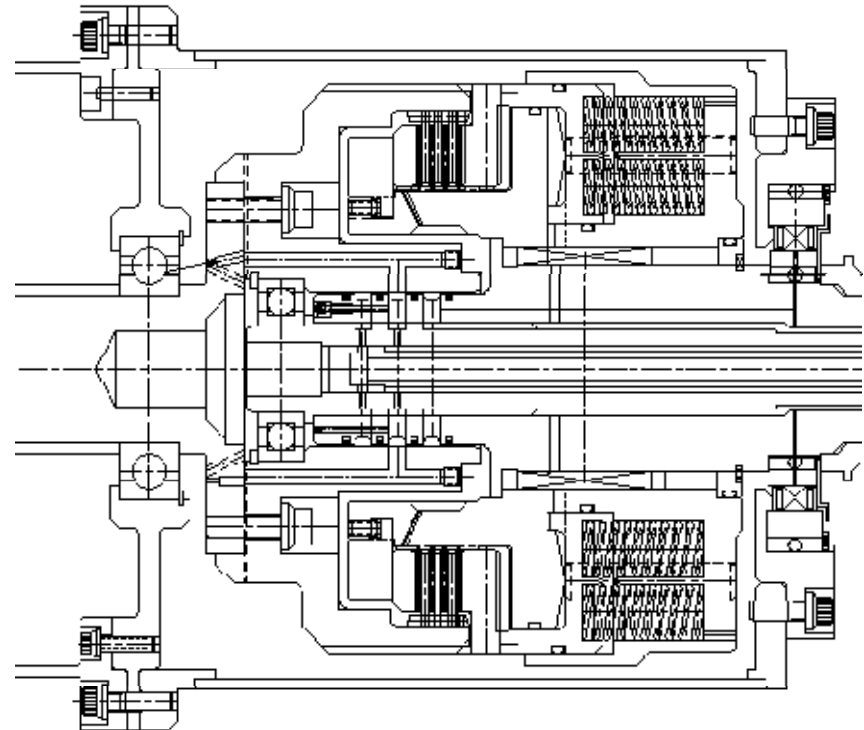
# Offset Compound Gear Drive w/ Dry Clutch



# Clutches



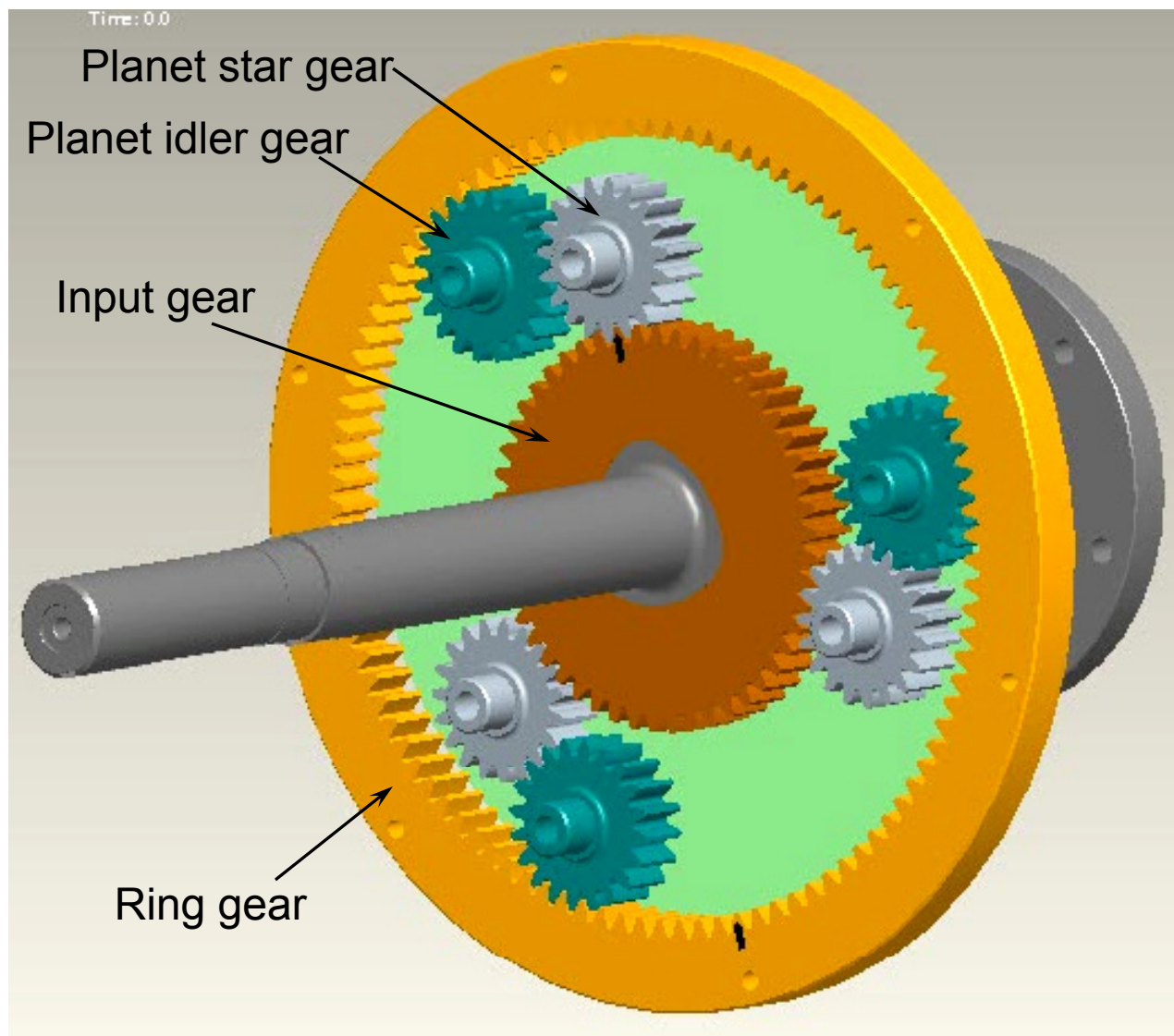
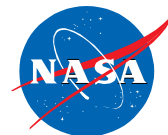
**Dry Clutch**

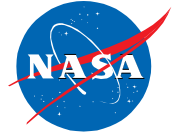


**Wet Clutch**



# Double Star Idler Planetary

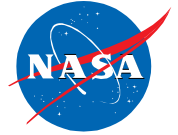




- **Development of variable-speed transmission test facility (in-house).**
- **Development of variable-speed transmission concepts (in-house, industry).**
- **Dynamic modeling of variable-speed drive systems (NASA NRA, Penn St, Univ. of Tennessee).**

# Drive System Dynamic Modeling

---



NASA/TM—2012-217212

AHS2011-000178



## Variable-Speed Simulation of a Dual-Clutch Gearbox Tiltrotor Driveline

*Hans DeSmidt*

*University of Tennessee, Knoxville, Tennessee*

*Kon-Well Wang*

*University of Michigan, Ann Arbor, Michigan*

*Edward C. Smith*

*Penn State University, University Park, Pennsylvania*

*David G. Lewicki*

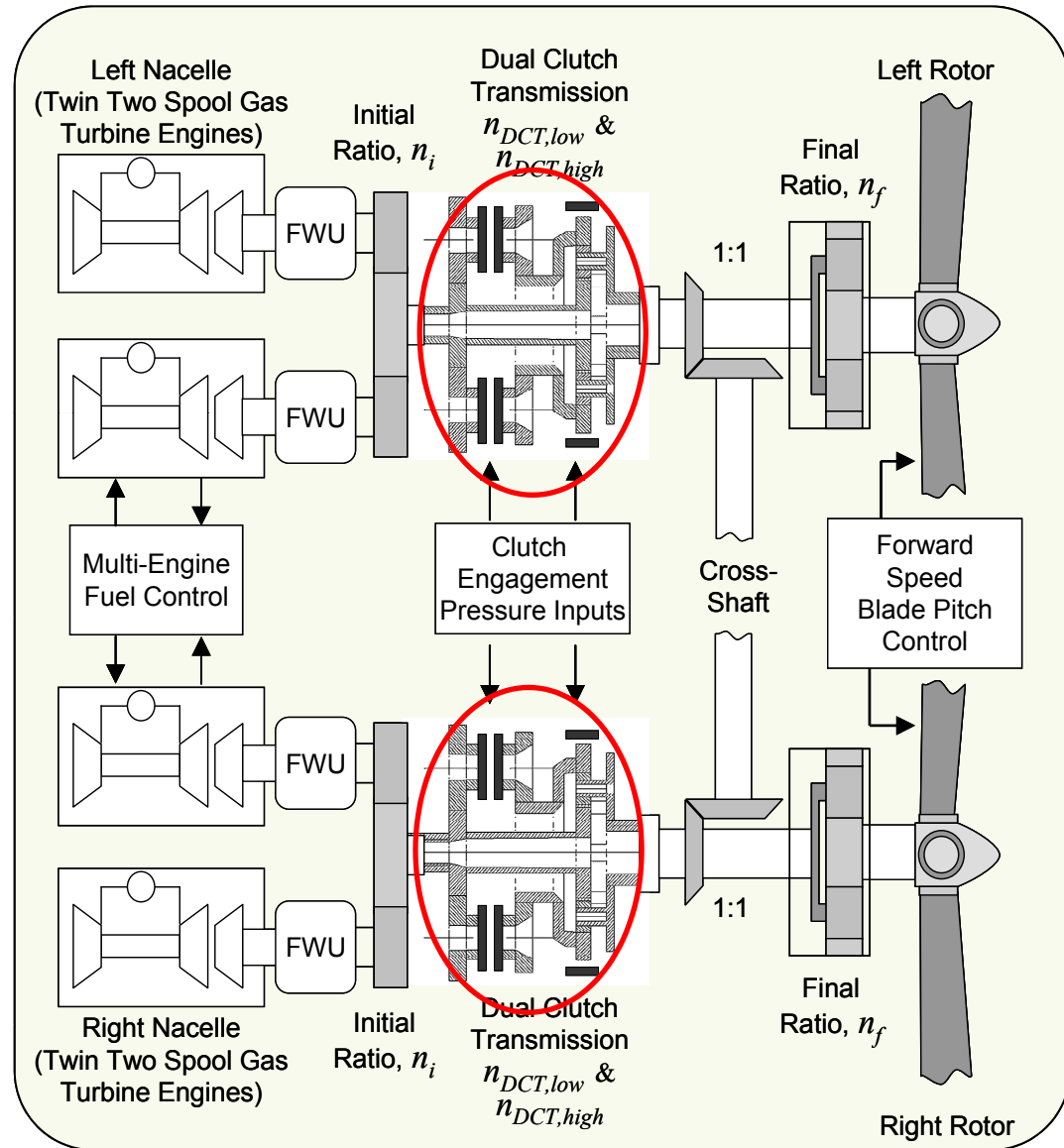
*Glenn Research Center, Cleveland, Ohio*

Prepared for the  
67th Annual Forum and Technology Display (Forum 67)  
sponsored by the American Helicopter Society (AHS)  
Virginia Beach, Virginia, May 3–5, 2011

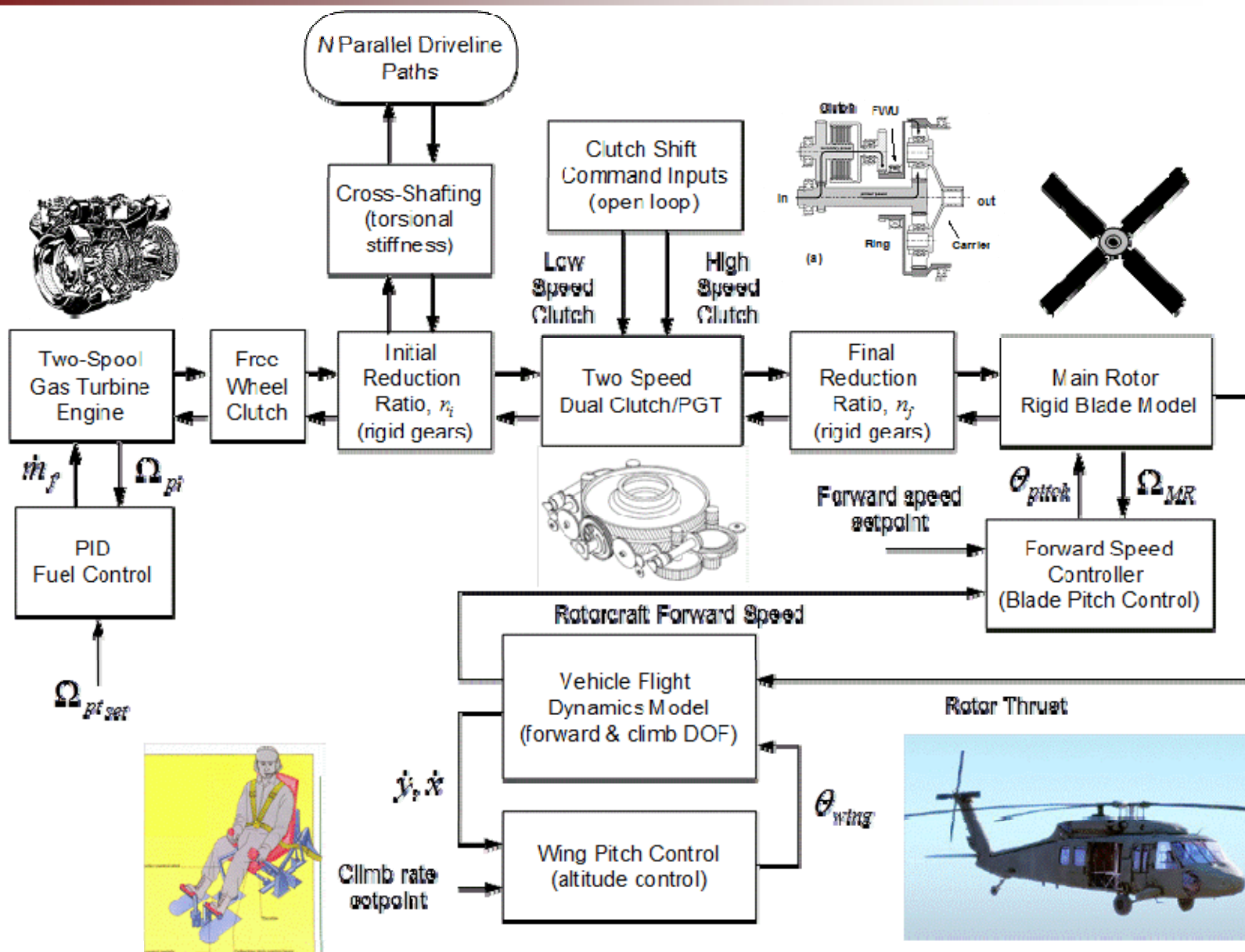
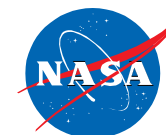
# Two-Speed Tiltrotor Driveline

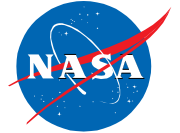


- DCTs upstream from cross-shaft
- Maintains rotor indexing phase



# Comprehensive Propulsion System Model





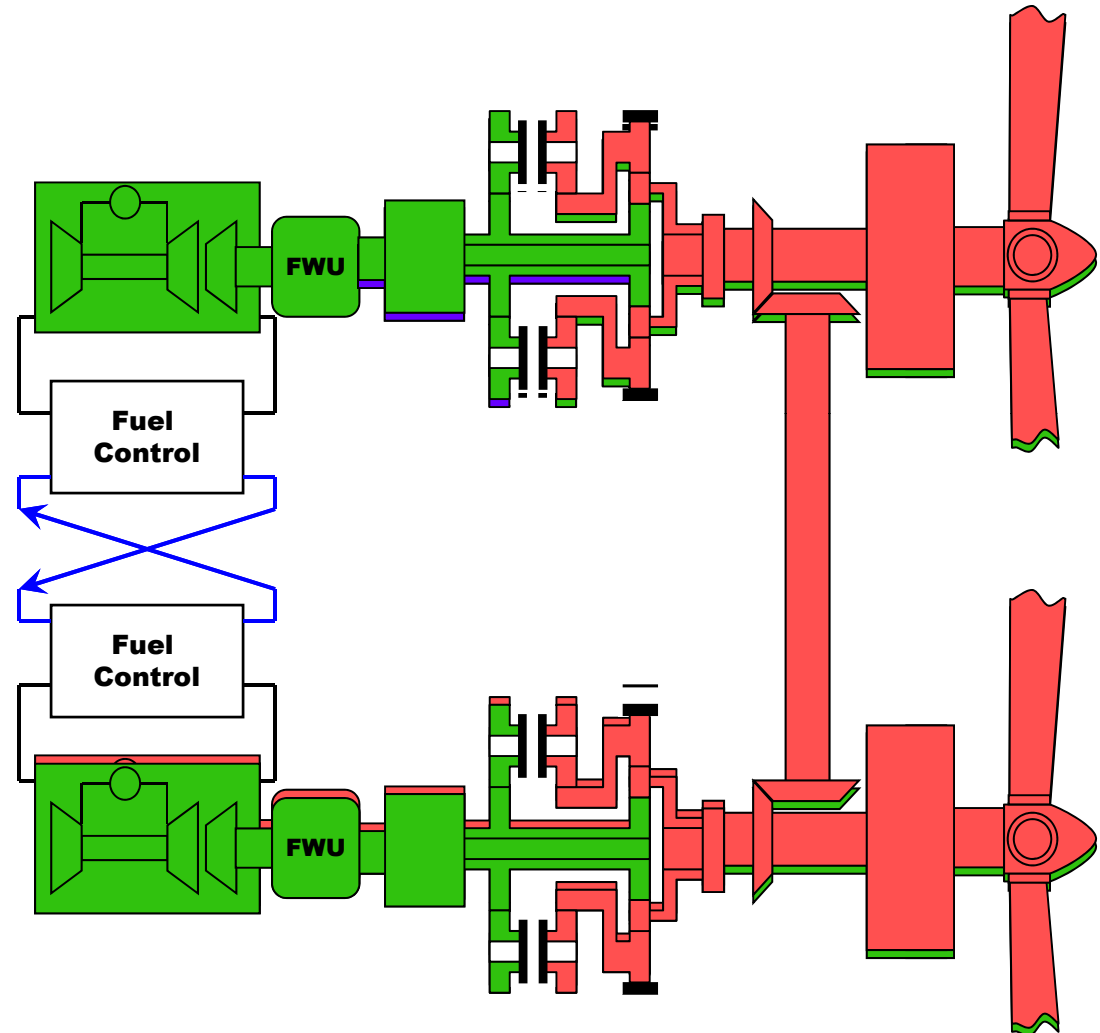
# Sequential Shift Control – Downshift

## SSC Downshift Sequence:

1. Disable GTE torque sharing control loop
2. Left side DCT downshift
3. Right side GTE ramp-down
4. Right side DCT downshift
5. Right side GTE ramp-up
6. Re-enable GTE torque sharing control loop

## Advantages:

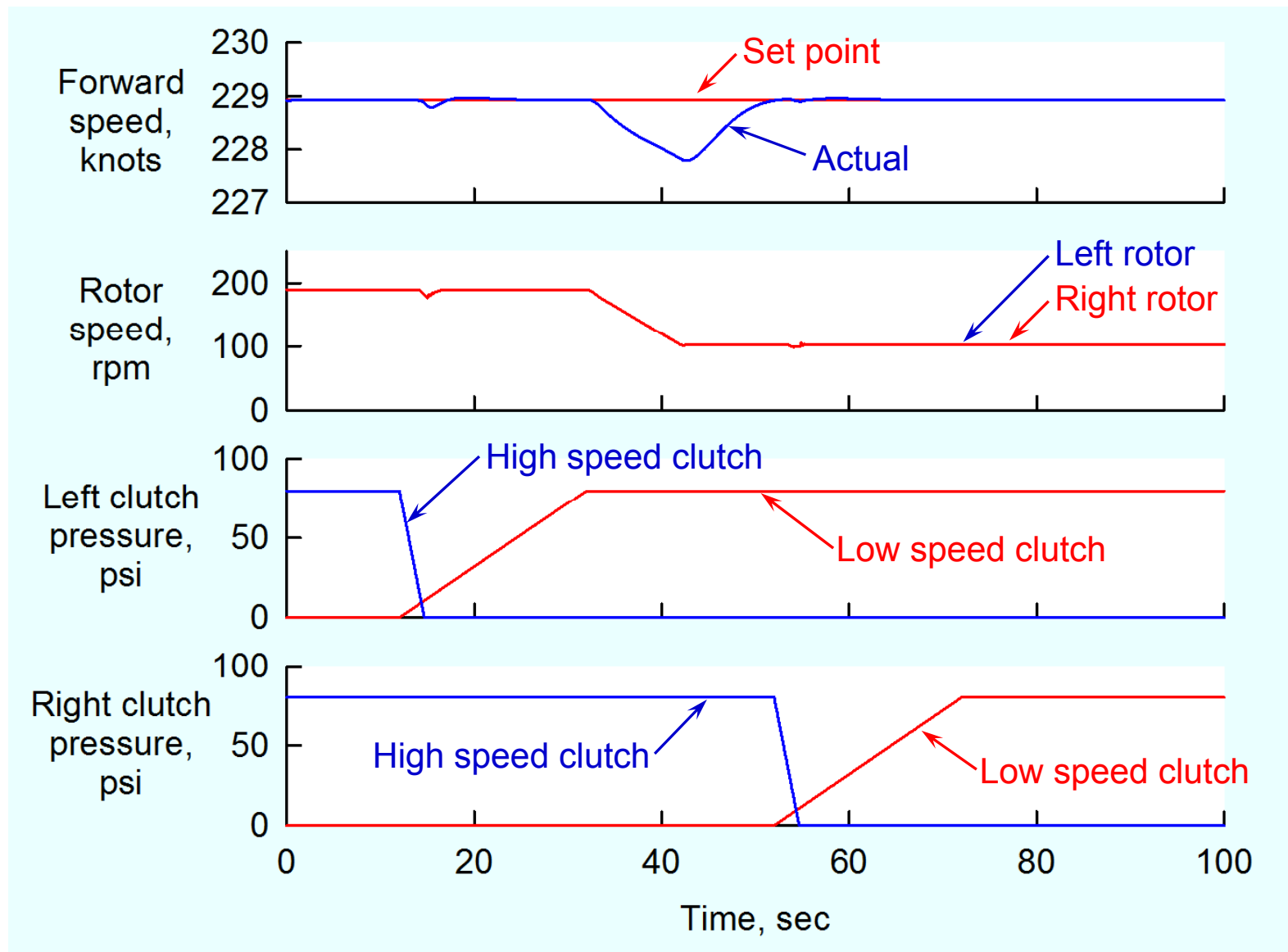
- Always under engine power
- Avoids clutch engagements under full power



Reference: Litt, J.S., Edwards, J.M., and DeCastro, J.A., "A Sequential Shifting Algorithm for Variable Rotor Speed Control," NASA/TM 2007-214842 (2007).



# Downshift Example Results



# Downshift Example Results

